

**IN THE CLAIMS:**

The text of all pending claims, (including withdrawn claims) is set forth below. Cancelled and not entered claims are indicated with claim number and status only. The claims as listed below show added text with underlining and deleted text with ~~strikethrough~~. The status of each claim is indicated with one of (original), (currently amended), (cancelled), (withdrawn), (new), (previously presented), or (not entered).

Please AMEND claims 1, 3, 5, 7, 9, 11, 12, 14, 16, 17, and 18 and CANCEL claims 2, 8, and 13 in accordance with the following:

1. (CURRENTLY AMENDED) A method of selling a commodity via a network, said method comprising:

transmitting to a user terminal, information concerning a recipe;

receiving from said user terminal, information concerning a cooking ingredient that is selected by a user of said user terminal and included in said recipe;

receiving from said user terminal, information concerning a physically existing shop selected by said user;

if-receiving from said user terminal instruction information regarding moving a-the selected article-cooking ingredient in at least one of a variety of positions for display and operating a camera included in a robot according to said moving-is received from a user terminal-, of the selected cooking ingredient, wherein said robot is provided for the selected physically existing shop and moves within said selected physically existing shop;

outputting to said robot, a first request for acquiring image information at this moment according to said moving of the-said selected article-cooking ingredient itself, -said robot provided for a real shop and moving around within said real shop; and

transmitting to said user terminal, said image information of the-said selected article cooking ingredient itself to enable said a-user of said-user terminal to evaluate an actual state of the-said selected article-cooking ingredient itself, said image information taken by said camera included in said robot;

receiving from said user terminal, information regarding a selected purchase plan commodity;

outputting to said robot, a second request for acquiring image information for said selected purchase plan commodity;

according to said second request, controlling said robot to move while taking image information until said robot reaches an exhibition position of said selected purchase plan commodity; and

transmitting to said user terminal, image information for said selected purchase plan commodity, which is taken by said camera included in said robot, image information until said robot reaches said exhibition position of said selected purchase plan commodity, and image information for a layout within said physically existing shop including a present position and a forwarding direction of said robot, to enable said user to see an actual state within said selected physically existing shop in real time.

2. (CANCELLED)

3. (CURRENTLY AMENDED) The method as set forth in claim 1, further comprising:

according to said first request, controlling said robot to change a photographing method for the-said selected cooking ingredientarticle-itself; and

receiving from said user terminal, if a purchase instruction of the-said selected article is received from said user terminalcooking ingredient; and

-instructing said robot to convey said selected article-cooking ingredient within said real physically existing shop.

4. (CANCELLED)

5. (CURRENTLY AMENDED) The method as set forth in claim 1, further comprising:

if-receiving from said user terminal, a purchase instruction of the-said selected article cooking ingredientis received from said user terminal;-

acquiring identification information of said selected article-cooking ingredient itself; and

transmitting said identification information of said selected article-cooking ingredient itself to said user terminal.

6. (CANCELLED)

7. (CURRENTLY AMENDED) A computer program embodied on a medium, for causing a computer to sell a commodity via a network, said program comprising:

transmitting to a user terminal, information concerning a recipe;  
receiving from said user terminal, information concerning a cooking ingredient that is selected by a user of said user terminal and included in said recipe;  
receiving from said user terminal, information concerning a physically existing shop selected by said user;

if-receiving from said user terminal instruction information regarding moving a-the selected article-cooking ingredient in at least one of a variety of positions for display and operating a camera included in a robot according to said moving of the selected cooking ingredient, wherein said robot is provided for the selected physically existing shop and moves around within said selected physically existing shop, is received from a user terminal,;

outputting to said robot, a first request for acquiring image information at this moment according to said moving of the selected article-cooking ingredient itself, said robot provided for a real shop and moving around within said real shop; and

transmitting to said user terminal, said image information of the selected article-cooking ingredient itself to enable a-said user of said user terminal to evaluate an actual state of the selected article-cooking ingredient itself, said image information taken by said camera included in said robot;

receiving from said user terminal, information regarding a selected purchase plan commodity;

outputting to said robot, a second request for acquiring image information for said selected purchase plan commodity;

according to said second request, controlling said robot to move while taking image information until said robot reaches an exhibition position of said selected purchase plan commodity; and

transmitting to said user terminal, image information for said selected purchase plan commodity, which is taken by said camera included in said robot, image information until said robot reaches said exhibition position of said selected purchase plan commodity, and image information for a layout within said physically existing shop including a present position and a forwarding direction of said robot, to enable said user to see an actual state within said selected physically existing shop in real time.

8. (CANCELLED)

9. (CURRENTLY AMENDED) The computer program as set forth in claim 7, further comprising:

according to said first request, controlling said robot to change a photographing method for the selected ~~article~~ cooking ingredient itself; and

~~if receiving from said user terminal a purchase instruction of the selected article~~ cooking ingredient ~~is received from said user terminal, and~~ instructing said robot to convey said selected ~~article~~ cooking ingredient within said ~~real~~ physically existing shop.

10. (CANCELLED)

11. (CURRENTLY AMENDED) The computer program as set forth in claim 7, further comprising:

~~if receiving from said user terminal, a purchase instruction of the selected article~~ is received ~~cooking ingredient from said user terminal,~~ acquiring identification information of said selected ~~article~~ cooking ingredient itself; and

transmitting said identification information of said selected ~~article~~ cooking ingredient itself to said user terminal.

12. (CURRENTLY AMENDED) A computer system for selling a commodity via a network, comprising:

a transmitter transmitting to a user terminal, information concerning a recipe;

a receiver receiving from said user terminal, information concerning a cooking ingredient that is selected by a user of said user terminal and included in said recipe, receiving from said user terminal, information concerning a physically existing shop selected by said user; and

~~a receiver receiving from said user terminal~~ instruction information regarding moving a the selected ~~article~~ cooking ingredient, from a user terminal ~~in at least one of a variety of positions for display and operating a camera included in a robot according to said moving of said selected cooking ingredient, wherein said robot is provided for the selected physically existing shop and moves around within said selected physically existing shop;~~

an outputting unit that outputs to said robot, a first request for acquiring image information at this moment according to said moving of said selected ~~article~~ cooking ingredient ~~itself, said robot provided for a real shop and moving around within said real shop; and~~

a transmitter transmitting to said user terminal, said image information of the selected

~~article-cooking ingredient~~ itself to enable a ~~said~~ user of ~~said user terminal~~ to evaluate an actual state of the selected ~~article-cooking ingredient~~ itself, said image information taken by said camera included in said robot;

receiving from said user terminal, information regarding a selected purchase plan commodity;

outputting to said robot, a second request for acquiring image information for said selected purchase plan commodity;

according to said second request, controlling said robot to move while taking image information until said robot reaches an exhibition position of said selected purchase plan commodity; and

transmitting to said user terminal, image information for said selected purchase plan commodity, which is taken by said camera included in said robot, image information until said robot reaches said exhibition position of said selected purchase plan commodity, and image information for a layout within said physically existing shop including a present position and a forwarding direction of said robot, to enable said user to see an actual state within said selected physically existing shop in real time.

13. (CANCELLED)

14. (CURRENTLY AMENDED) The computer system as set forth in claim 12, further comprising:

a second controller controlling said robot to change a photographing method for the selected ~~article-cooking ingredient~~ itself, according to said first photographing request;

a third receiver receiving from said user terminal, a purchase instruction of the ~~said~~ selected ~~article-cooking ingredient from said user terminal~~; and

a third controller instructing said robot to convey said selected ~~article-cooking ingredient~~ within said ~~real-physically existing~~ shop in response to said purchase instruction.

15. (CANCELLED)

16. (CURRENTLY AMENDED) The computer system as set forth in claim 12, further comprising:

a fourth receiver for receiving from said user terminal a purchase instruction of the selected ~~article-cooking ingredient from said user terminal~~;

an acquiring unit that acquires identification information of said selected ~~article~~ cooking ingredient itself in response to said purchase instruction; and

a third transmitter transmitting said identification information of said selected ~~article~~ cooking ingredient itself to said user terminal.

17. (CURRENTLY AMENDED) The method as set forth in claim 1, further comprising:

~~if receiving from said user terminal~~ third instruction information regarding a selection of another article of said one commodity ~~is received from said user terminal;~~

outputting to said robot, a third request for acquiring image information for said another article at this moment according to said third instruction information; and

transmitting to said user terminal, said image information for said another article to enable said user of said user terminal to evaluate an actual state of said another article itself, said image information taken by said camera included in said robot.

18. (CURRENTLY AMENDED) The method as set forth in claim 1, further comprising:

~~if receiving~~ a voice request ~~is received;~~

outputting to said robot including a microphone, an instruction to obtain voice information within said real shop; and

transmitting to said user terminal, the obtained voice information to enable said user of said user terminal to represent an actual state within said real shop in real time.

19. (PREVIOUSLY PRESENTED) A method of selling an item, comprising:

receiving instruction information at a robot including information pertaining to manipulating a selected object to place the object in at least one of a variety of directional orientations, said instruction information including information pertaining to obtaining an image according to said manipulating; and

receiving a purchase instruction based on an evaluation resulting from inspection of said object as said object appears in said image.